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RECONSTRUCTION OF A 3-MANIFOLD  
BY A NON-SINGULAR FLOW

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1. SPINES INDUCED BY A NON-SINGULAR FLOW

Let  $M$  be a smooth and closed 3-manifold, and  $\psi_t$  be a non-singular flow on  $M$ . Take a compact local section  $\Sigma$  of  $\psi_t$  so that it is homeomorphic to a compact 2-disk and intersects with every orbit of  $\psi_t$ . For such a pair  $(\psi_t, \Sigma)$  we define functions  $T_+(x)$  and  $T_-(x)$  by

$$T_+(x) = \inf \{ t > 0 \mid \psi_t(x) \in \Sigma \}$$

$$T_-(x) = \sup \{ t < 0 \mid \psi_t(x) \in \Sigma \}.$$

Moreover define  $\hat{T}_\pm(x)$  to be  $\hat{T}_\pm(x) = \psi_\sigma(x)$  ( $\sigma = T_\pm(x)$ ).

We can take  $\Sigma$  so that it satisfies that

- (i)  $\partial\Sigma$  is  $\psi_t$ -transversal at  $(x, T_+(x))$  for any  $x \in M$  (see [2] for the definition of  $\psi_t$ -transversality), and
- (ii) if  $x \in \partial\Sigma$  and  $x_1 = \hat{T}_+(x) \in \partial\Sigma$ , then  $\hat{T}_+(x_1)$  is included in  $\text{int}(\Sigma)$ .

We call a pair  $(\psi_t, \Sigma)$  with the above conditions a normal pair.

For a normal pair  $(\psi_t, \Sigma)$ , the flow-spines  $P_- = P_-(\psi_t, \Sigma)$

and  $P_+ = P_+(\psi_t, \Sigma)$  are defined by

$$P_- = \Sigma \cup \{\psi_t(x) \mid x \in \partial\Sigma, T_-(x) \leq t \leq 0\}$$

$$P_+ = \Sigma \cup \{\psi_t(x) \mid x \in \partial\Sigma, 0 \leq t \leq T_+(x)\}.$$

Each of  $P_-$  and  $P_+$  is a closed fake surface and forms a standard spine of  $M$  (cf. [1]). The set  $S_j(P_-)$  ( $j = 2, 3$ ) of the  $j$ -th singularities of  $P_-$  are given by

$$S_3(P_-) = \{x \in \text{int}(\Sigma) \mid \hat{T}_+(x) \text{ and } \hat{T}_+^2(x) \text{ are both on } \partial\Sigma\}$$

$$S_2(P_-) = \hat{T}_-(\partial\Sigma) \cup \{\psi_t(x) \mid x \in S_3(P_-), 0 \leq t \leq T_+(x)\}$$

(see [1] and [2] for the precise).

## 2. RECONSTRUCTION OF $M$ .

Let  $B = \{(x, y, z) \mid x^2 + y^2 + z^2 \leq 1\}$  be the unit 3-ball in  $\mathbb{R}^3$ ,  $\rho : \partial B \rightarrow \partial B$  be a map defined by  $\rho(x, y, z) = (x, y, -z)$ , and  $\iota$  be an embedding of  $\Sigma$  into  $S^2 = \partial B$  such that  $\iota(\partial\Sigma) = \partial B \cap \{z = 0\}$ . We define an equivalence relation " $\sim$ " on  $\partial B$  as follows:

(i) for  $x \in S_3(P_-) \subset \text{int}(\Sigma)$ ,

$$\iota(x) \sim \iota(\hat{T}_+(x)) \sim \iota(\hat{T}_+^2(x)) \sim \iota(\rho(\hat{T}_+^3(x)))$$

(ii) for  $x \in \text{int}(\Sigma) \cap (\hat{T}_-(\partial\Sigma) - S_3(P_-))$ ,

$$\iota(x) \sim \iota(\hat{T}_+(x)) \sim \iota(\rho(\hat{T}_+^2(x)))$$

(iii) for  $x \in \text{int}(\Sigma) - \hat{T}_+^2(\partial\Sigma)$ ,

$$\iota(x) \sim \iota(\rho(\hat{T}_+(x)))$$

Then we get the following theorem which gives a polyhedral representation of  $M$ .

THEOREM 1 ([2]).

M is homeomorphic to  $B/\sim$  , and each of  $P_-$  and  $P_+$  is homeomorphic to  $\partial B/\sim$  .

## 3. AN APPLICATION

We consider a normal pair for which the following condition (B) is satisfied.

- (B)  $\hat{T}_+(S_3(P_-))$  and  $\hat{T}_+^2(S_3(P_-))$  are separated by two points, namely, there are two points  $z_1$  and  $z_2$  on  $\partial\Sigma$  such that  $\hat{T}_+(S_3(P_-))$  is included in one of the components of  $\partial\Sigma - \{z_1, z_2\}$  and  $\hat{T}_+^2(S_3(P_-))$  is in the other.

This condition is a generalization of the condition (A) in [4] . And, using the reducing method shown in [3] and [4], we can deform a normal pair with (B) into one giving a polyhedral representation of some normal form which include those given by Fig.7 in [4]. As examples, we exhibit in Fig.1 and 2 the normal form obtained by the above way which represent the lens space  $L(5, 1)$  and  $L(5, 2)$  respectively. In general, we can prove that the polyhedral representation of these normal form yield  $S^3$  or  $S^2 \times S^1$  or lens space  $L(p, q)$  . Conversely, using the method in [4], we can construct a normal pair with the condition (B) on these manifolds. Thus we have

THEOREM 2.

$M$  admits a normal pair satisfying (B) if and only if  
 $M = S^3$  or  $S^2 \times S^1$  or  $L(p, q)$  .

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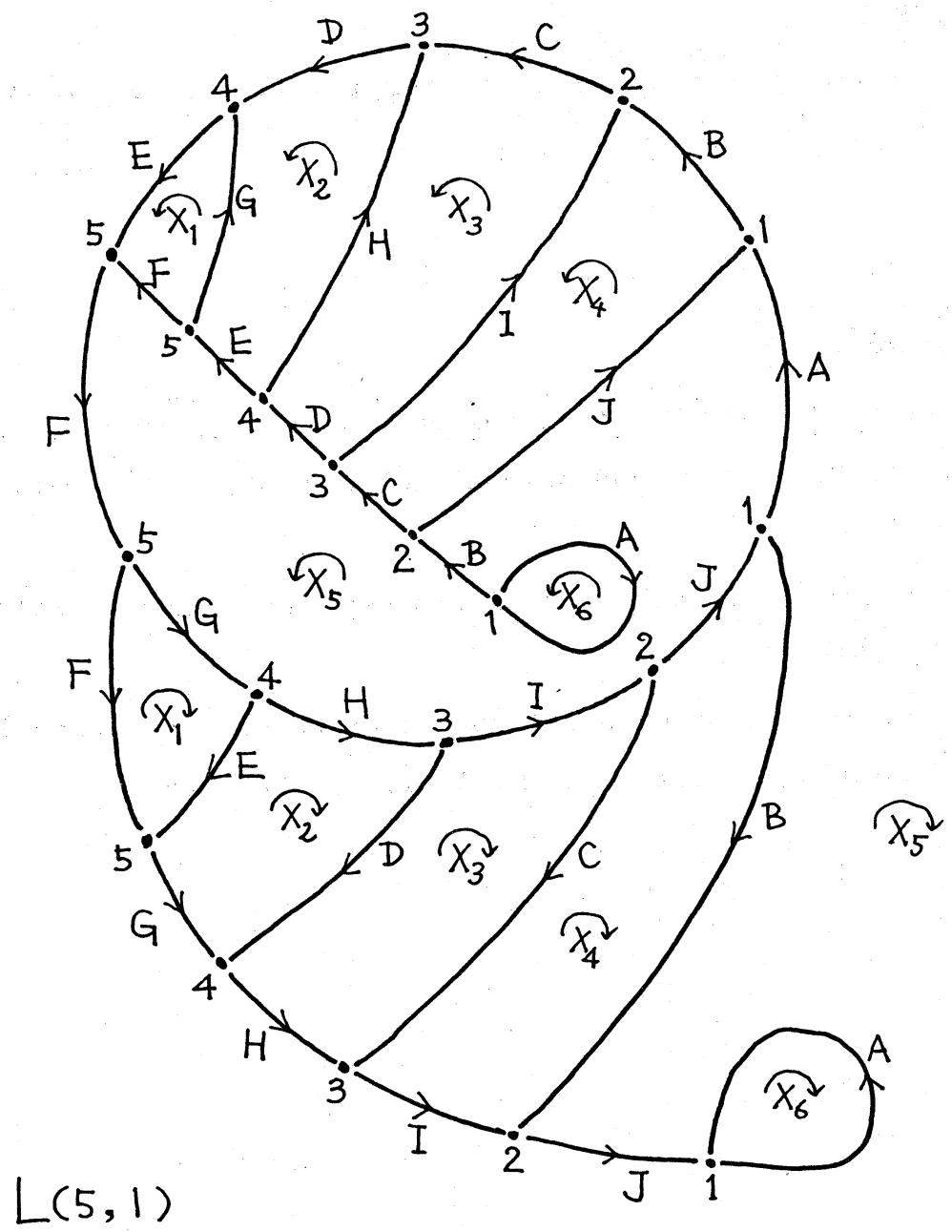


Fig. 1

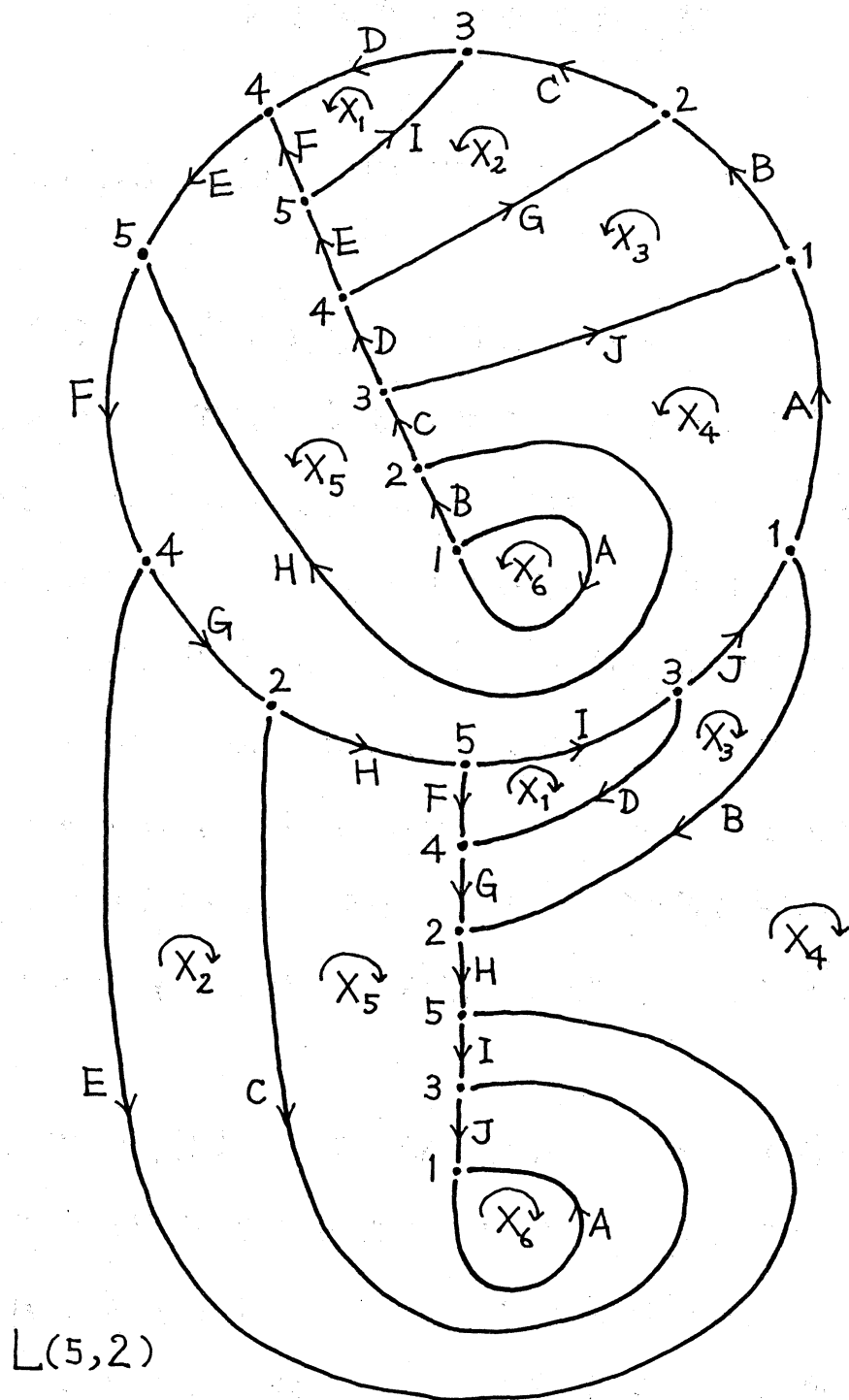


Fig. 2